Hi-C 2.1 Data Levels User Guide

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1. Acknowledgement Statement

Please include the following acknowledgement statement in publications using the Hi-C 2.1 data set.

We acknowledge the High-resolution Coronal Imager (Hi-C 2.1) instrument team for making the second re-flight data available under NASA Heliophysics Technology and Instrument Development for Science (HTIDS) Low Cost Access to Space (LCAS) program). MSFC/NASA led the mission with partners including the Smithsonian Astrophysical Observatory, the University of Central Lancashire, and Lockheed Martin Solar and Astrophysics Laboratory.

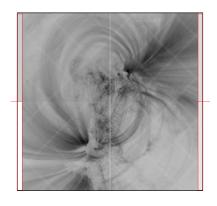
2. Data Products

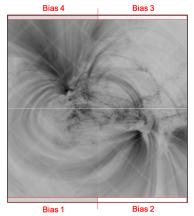
^{*} Readily available through the VSO. Otherwise available by request (Sabrina dot Savage at nasa dot gov or Amy dot R dot Winebarger at nasa dot gov).

3. Graphic Summary of Basic Level Outputs

Level 0

Raw Incorrect Times Incorrect Header Info Incorrect Orientation



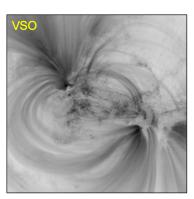


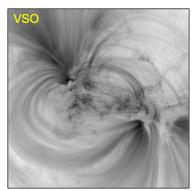
<u>Level 0.5</u>

Level 0+
Rotated 90 deg CCW
Time stamp corrected
Header coordinates updated
Center coordinates updated
(including rotational drift)
Fine co-alignment shifts
incorporated
Corrected and expanded
header Info

Level 1.0

Level 0.5+
Master Dark-Subtracted
Bias-Subtracted per quadrant
using non-active pixels
(quadrant bias levels
added to header)
Flat-fielded to remove grid
Cleaned of bad pixels & dust
Cropped to remove side nonactive pixels and center
overscan regions





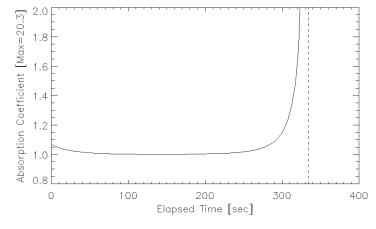
Level 1.5

Level 1.0+ Shifted to be co-aligned based on header coordinates and with tracking applied Absorption-compensated

4. Additional Notes

a) Atmospheric Absorption

The absorption coefficients are calculated empirically and are added to the Level 1.5 headers under the keyword abscoef. The images are compensated by multiplying the counts by these values.



b) Gain

Counts are in units of Data Number. The gain is approximately 2.5 electrons / DN. More precise gain measurements are available upon request.

c) Jitter

There is substantial jitter from the rocket in about half of the frames. We are working to de-smear these images; however, in the meantime, arrays of good and bad indices are provided with the data as 'good bad indices.sav'.

```
IDL> restore, 'good_bad_indices.sav', /v

→ Arrays = goodis and badis
e.g., goodmap15 = hic21_l15_map[goodis]
-or-
IDL> mreadfits, fits_files, index, data
IDL> index = index[goodis] & data = data[*,*,goodis]
```